

**Joint IMD-WMO group fellowship Training On Numerical Weather  
Prediction  
By  
Meteorological Training Institute, India Meteorological Department  
(IMD), Pune**

**Atmospheric Boundary Layer (ABL) and its  
Parameterizations - Part III**

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**19 & 20 October 2021**

# 1. References

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**2. An Introduction to Boundary Layer Meteorology - R. B. Stull  
(Kluwer Academic Publishers) \***

**3. An Introduction to Fluid Dynamics - G. K. Batchelor  
(Cambridge University Press)**

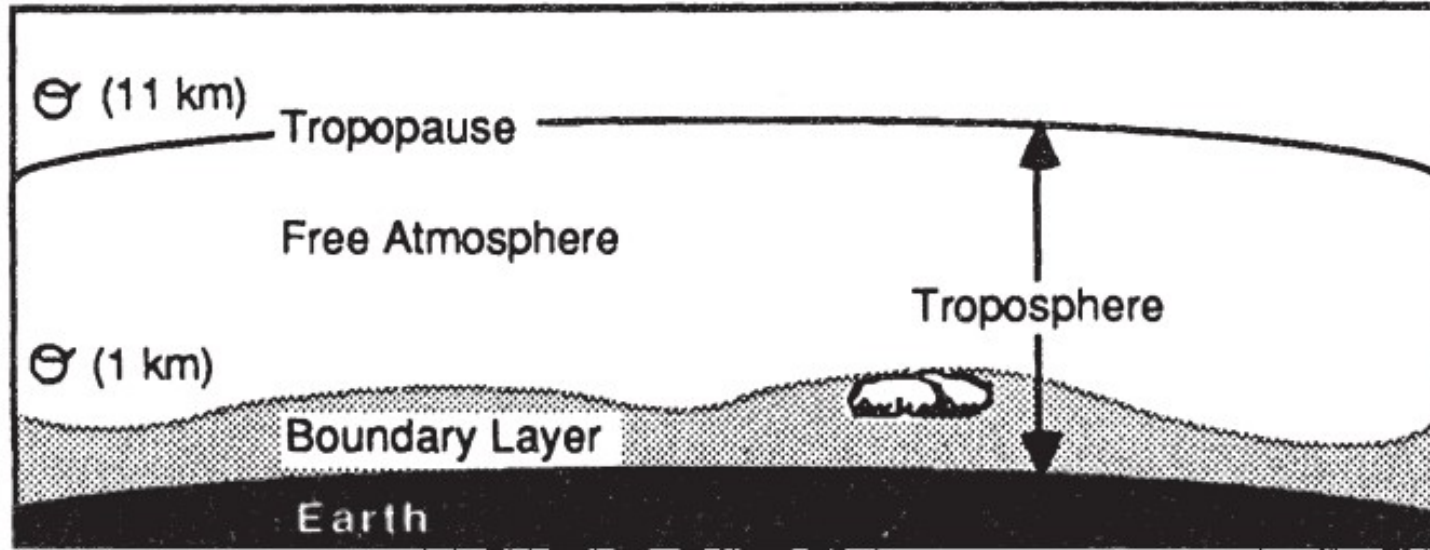
# 1. References

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(McGraw-Hill Book Company)**

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(Oxford University Press)**

**6. Fluid Mechanics - Kundu and Cohen  
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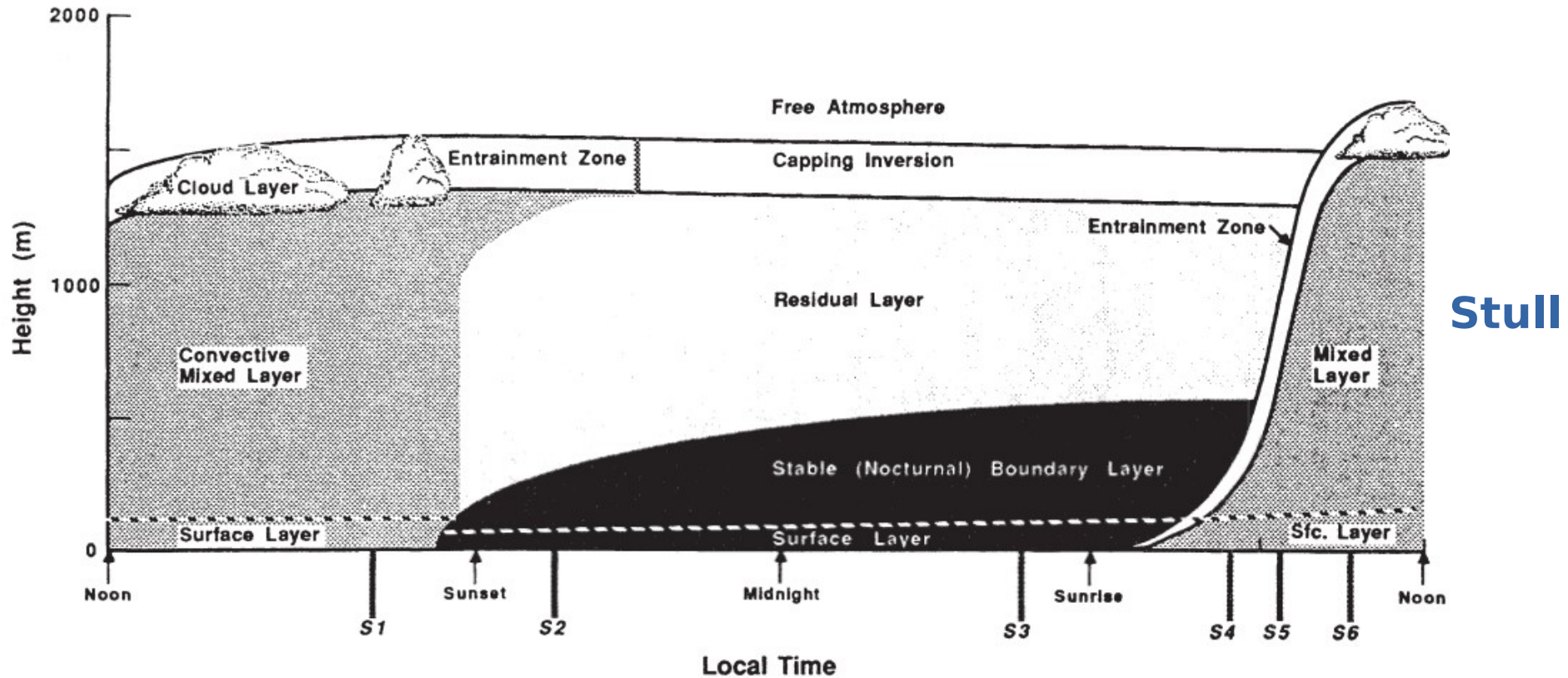
## 2. Atmospheric Boundary Layer



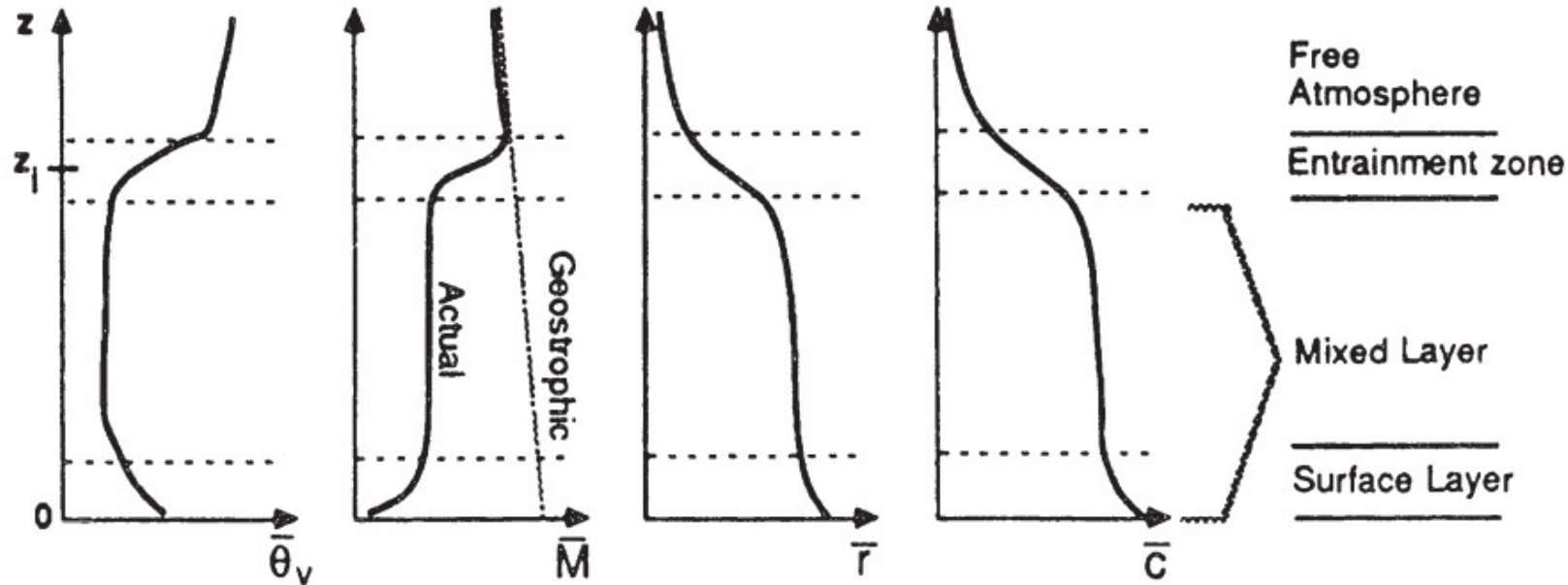
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Fig. 1.1 The troposphere can be divided into two parts: a boundary layer (shaded) near the surface and the free atmosphere above it.

## 2. Atmospheric Boundary Layer



## 2. Atmospheric Boundary Layer



Stull

**Fig. 1.9** Typical daytime profiles of mean virtual potential temperature  $\bar{\theta}_v$ , wind speed  $\bar{M}$  (where  $\bar{M}^2 = \bar{u}^2 + \bar{v}^2$ ), water vapor mixing ratio  $\bar{r}$ , and pollutant concentration  $\bar{c}$ .

## 2. Atmospheric Boundary Layer

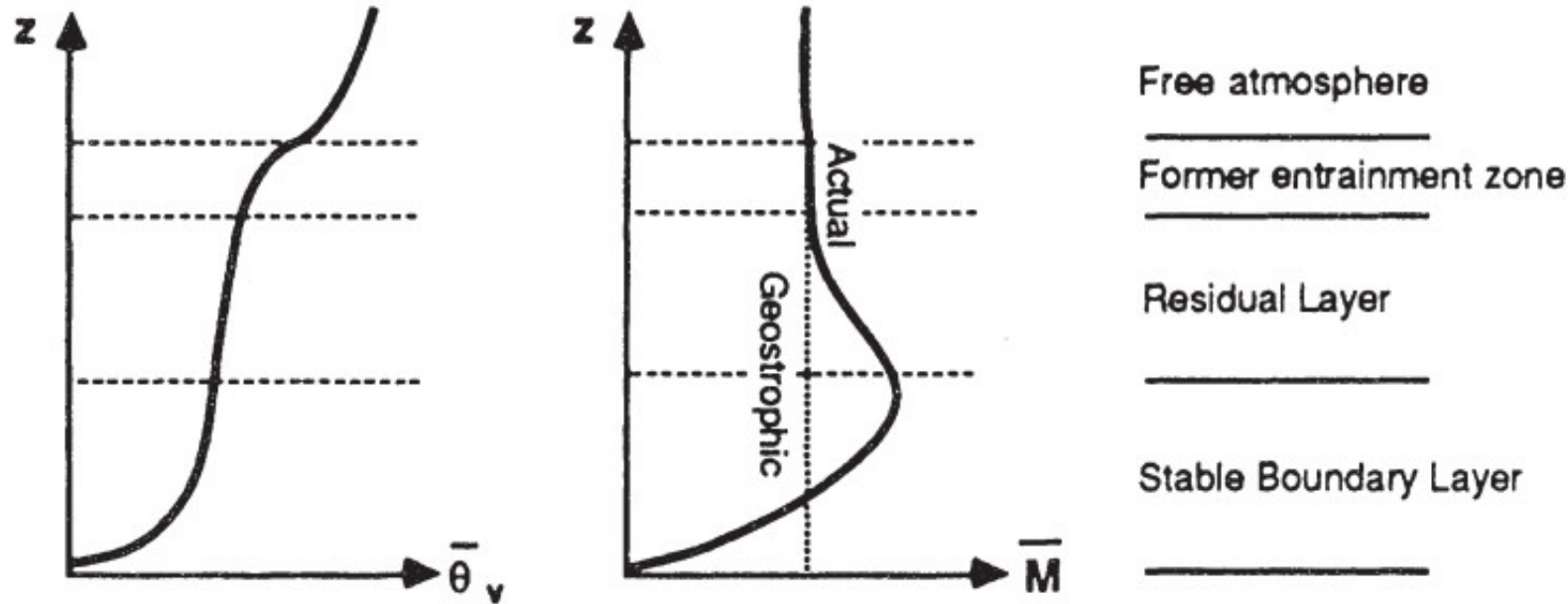
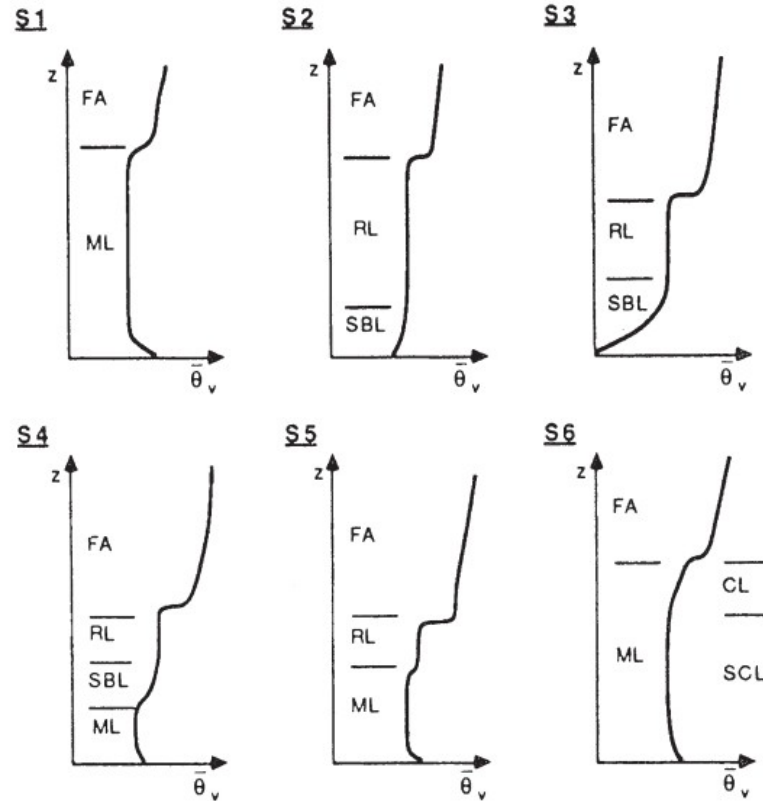


Fig. 1.11 Mean virtual potential temperature,  $\bar{\theta}_v$ , and wind speed,  $\bar{M}$ , profiles for an idealized stable boundary layer in a high-pressure region.

Stull

## 2. Atmospheric Boundary Layer

**Fig. 1.12**  
Profiles of mean virtual potential temperature,  $\bar{\theta}_v$ , showing the boundary-layer evolution during a diurnal cycle starting at about 1600 local time. S1-S6 identify each sounding with an associated launch time indicated in Fig. 1.7.



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## 2. Stability Parameters

$$R_f = \frac{\left(\frac{g}{\theta_v}\right) \overline{(w'\theta_v')}}{\overline{(u_i'u_j')}} \frac{\partial \bar{U}_i}{\partial x_j}$$

**Flux Richardson  
Number**

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$$R_f = \frac{\left(\frac{g}{\theta_v}\right) \overline{(w'\theta_v')}}{\overline{(u'w')}} \frac{\partial \bar{U}}{\partial z} + \overline{(v'w')} \frac{\partial \bar{V}}{\partial z}$$

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$$R_f = \frac{\left(\frac{g}{\theta_v}\right) (\overline{w'\theta_v'})}{(\overline{u_i'u_j'}) \frac{\partial \overline{U}_i}{\partial x_i}}$$

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$$R_f = \frac{\left(\frac{g}{\theta_v}\right) (\overline{w'\theta_v'})}{(\overline{u'w'}) \frac{\partial \overline{U}}{\partial z} + (\overline{v'w'}) \frac{\partial \overline{V}}{\partial z}}$$

$$Ri = \frac{\frac{g}{\theta_v} \frac{\partial \overline{\theta}_v}{\partial z}}{\left[ \left(\frac{\partial \overline{U}}{\partial z}\right)^2 + \left(\frac{\partial \overline{V}}{\partial z}\right)^2 \right]}$$

**Gradient Richardson Number**

## 2. Stability Parameters

$$R_f = \frac{\left(\frac{g}{\theta_v}\right) \overline{(w'\theta_v')}}{\overline{(u_i'u_j')}} \frac{\partial \bar{U}_i}{\partial x_i}$$

**Flux Richardson Number**

$$R_f = \frac{\left(\frac{g}{\theta_v}\right) \overline{(w'\theta_v')}}{\overline{(u'w')}} \frac{\partial \bar{U}}{\partial z} + \overline{(v'w')} \frac{\partial \bar{V}}{\partial z}$$

$$Ri = \frac{\frac{g}{\theta_v} \frac{\partial \bar{\theta}_v}{\partial z}}{\left[ \left(\frac{\partial \bar{U}}{\partial z}\right)^2 + \left(\frac{\partial \bar{V}}{\partial z}\right)^2 \right]}$$

**Gradient  
Richardson  
Number**

**Bulk  
Richardson  
Number**


$$R_B = \frac{g \Delta \bar{\theta}_v \Delta z}{\theta_v [(\Delta \bar{U})^2 + (\Delta \bar{V})^2]}$$

## 2. Stability Parameters

$$R_f = \frac{\left(\frac{g}{\theta_v}\right) \overline{(w'\theta_v')}}{\overline{(u_i'u_j')}} \frac{\partial \bar{U}_i}{\partial x_j}$$

**Flux Richardson  
Number**

**Applied in the  
Surface Layer**


$$\overline{u_i u_j} \sim U_*^2, \quad \partial U_i / \partial x_j \sim U_* / \kappa z$$

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$$\overline{u_i u_j} \sim U_*^2, \quad \partial U_i / \partial x_j \sim U_* / \kappa z$$

$$\zeta = \frac{z}{L} = \frac{-k z g \overline{(w'\theta_v')}}{\overline{\theta_v} u_*^3}$$

**“L” is the Obukhov length**

**“z” is the height of the measurement  
location in the Surface Layer**

## 2. Stability Parameters

$$L = -\frac{\overline{\theta}_v U_*^3}{\kappa g (\overline{w'\theta'_v})_s}$$

$$\zeta = \frac{z}{L}$$

$\zeta < 0$ , unstable

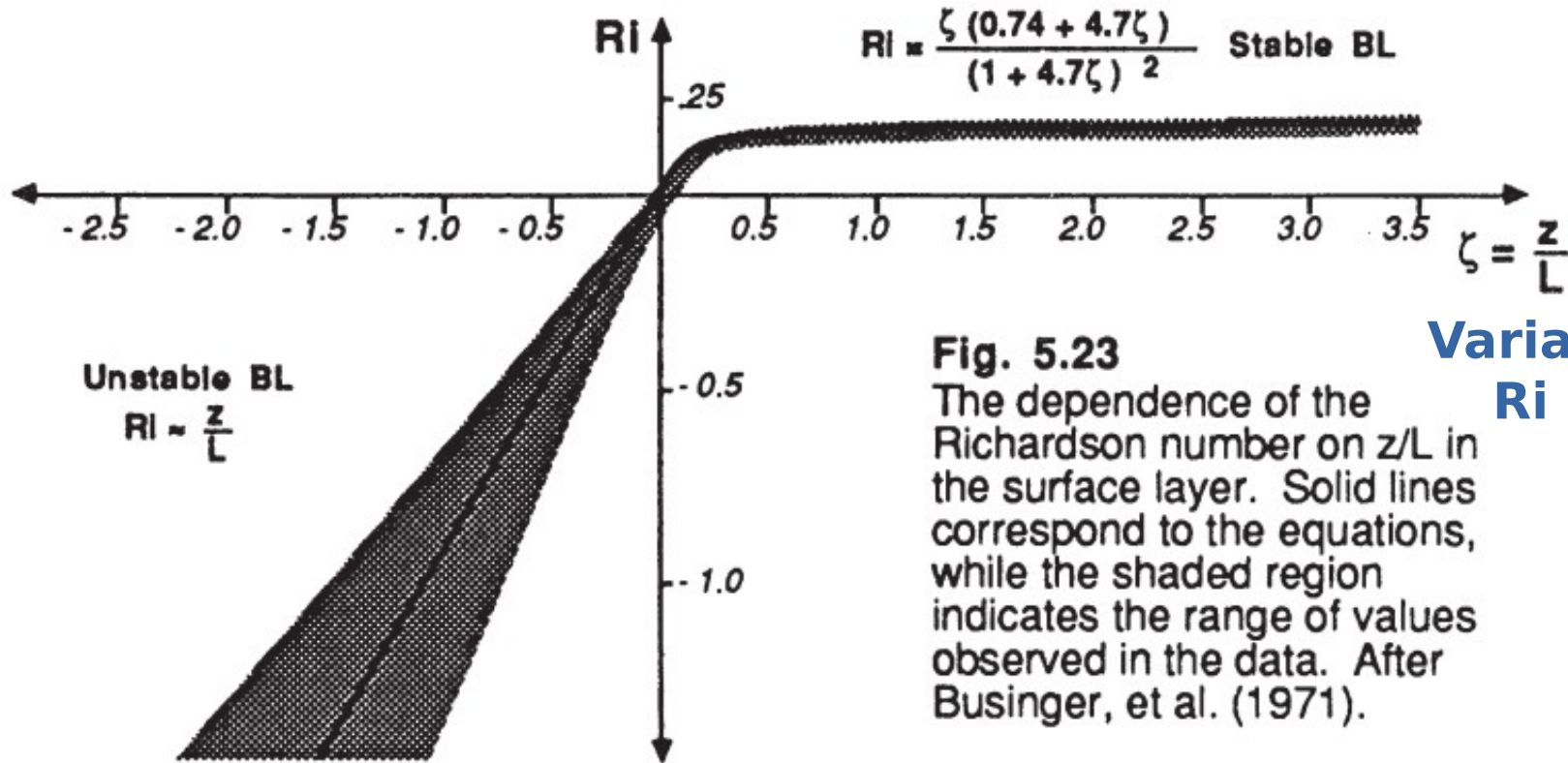
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“L” is the Obukhov length

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Surface Layer  
stability  
parameter

## 2. Stability Parameters



**Fig. 5.23**

The dependence of the Richardson number on  $z/L$  in the surface layer. Solid lines correspond to the equations, while the shaded region indicates the range of values observed in the data. After Businger, et al. (1971).

**Variation of  $z/L$  with  $Ri$  (Gradient  $Ri$ )**



## 2. Stability Parameters

$$w_* = \left[ \frac{g z_i}{\theta_v} \left( \overline{w' \theta_v'} \right)_s \right]^{1/3}$$

**Convective Velocity Scale**  
 **$z_i$  is the height of the top of the ML**

$\overline{w' \theta_v'} > 0$ , convective i.e. heat flux upward from the surface

$$\zeta = \frac{z}{L} = -\frac{k z w_*^3}{z_i u_*^3}$$

**Surface Layer stability parameter in terms of convective and shear velocity scales**

## 2. Stability Parameters

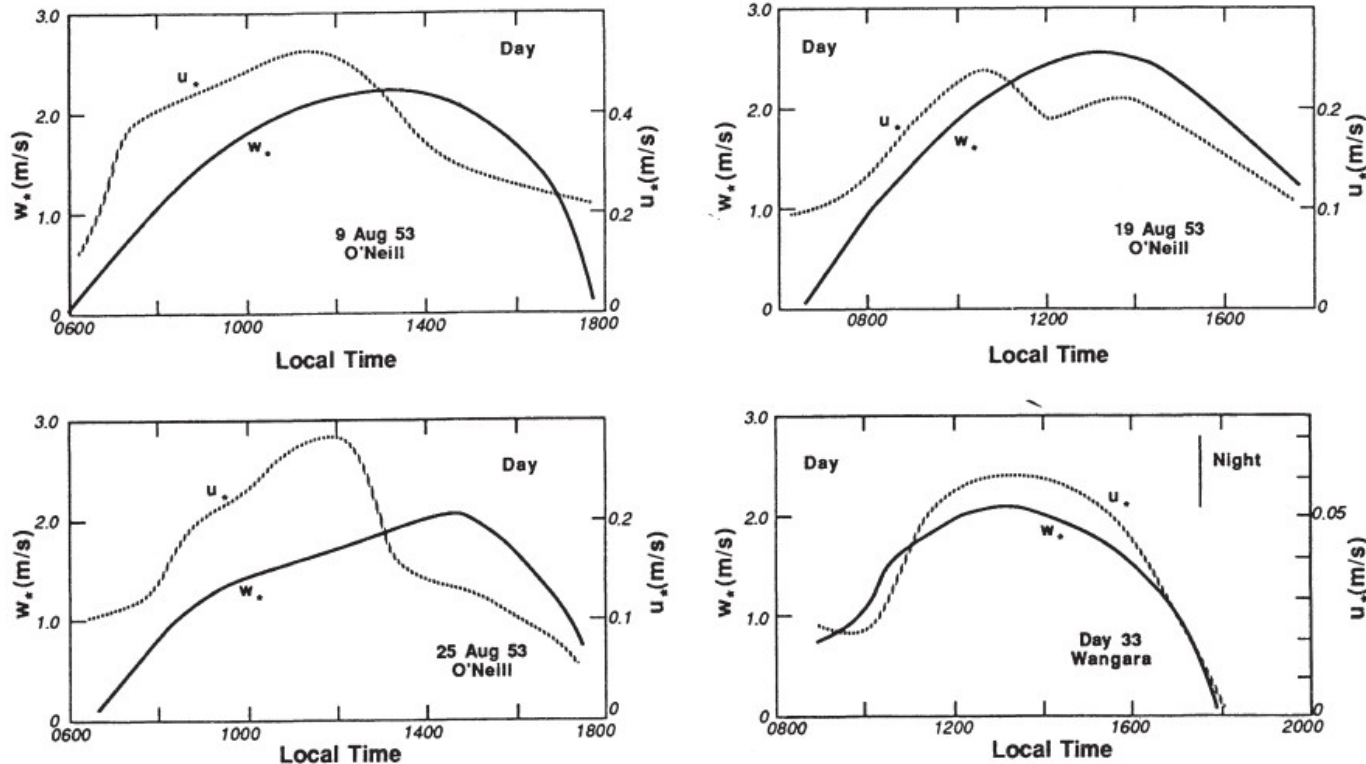


Fig. 4.1 Sample variations of the friction velocity,  $u_*$ , and the convective scaling velocity,  $w_*$ , with time for the O'Neill, (Nebraska) and Wangara (Australia) field programs.

Stull  
Diurnal variation of  
 $w_*$  and  $U^*$

### 3. TKE Budget in the ABL

$$\frac{\overline{\partial u_i'^2}}{\partial t} + \overline{U_j} \frac{\partial \overline{u_i'^2}}{\partial x_j} = + 2 \delta_{i3} \frac{\overline{g(u_i' \theta_v')}}{\overline{\theta_v}} - 2 \overline{u_i' u_j'} \frac{\partial \overline{U_i}}{\partial x_j} - \frac{\partial (\overline{u_j' u_i'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{u_i' p'})}{\partial x_i} - 2\varepsilon$$

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$$\frac{\overline{\partial u'^2}}{\partial t} + \overline{U_j} \frac{\partial \overline{u'^2}}{\partial x_j} = - 2 \overline{u' u_j'} \frac{\partial \overline{U}}{\partial x_j} - \frac{\partial (\overline{u_j' u'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{u' p'})}{\partial x} + \frac{2 \overline{p'}}{\overline{\rho}} \frac{\partial \overline{u'}}{\partial x} - 2 \nu \overline{\left( \frac{\partial u'}{\partial x_j} \right)^2}$$

### 3. TKE Budget in the ABL

$$\begin{aligned}
 \frac{\partial \overline{u_i'^2}}{\partial t} + \overline{U}_j \frac{\partial \overline{u_i'^2}}{\partial x_j} &= + 2 \delta_{i3} \frac{\overline{g(u_i' \theta_v')}}{\overline{\theta_v}} - 2 \overline{u_i' u_j'} \frac{\partial \overline{U}_i}{\partial x_j} - \frac{\partial (\overline{u_j' u_i'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{u_i' p'})}{\partial x_i} - 2\varepsilon \\
 \frac{\partial \overline{u'^2}}{\partial t} + \overline{U}_j \frac{\partial \overline{u'^2}}{\partial x_j} &= - 2 \overline{u' u_j'} \frac{\partial \overline{U}}{\partial x_j} - \frac{\partial (\overline{u_j' u'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{u' p'})}{\partial x} + \frac{2 \overline{p'} \partial u'}{\overline{\rho} \partial x} - 2 \overline{v \left( \frac{\partial u'}{\partial x_j} \right)^2} \\
 \frac{\partial \overline{v'^2}}{\partial t} + \overline{U}_j \frac{\partial \overline{v'^2}}{\partial x_j} &= - 2 \overline{v' u_j'} \frac{\partial \overline{V}}{\partial x_j} - \frac{\partial (\overline{u_j' v'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{v' p'})}{\partial y} + \frac{2 \overline{p'} \partial v'}{\overline{\rho} \partial y} - 2 \overline{v \left( \frac{\partial v'}{\partial x_j} \right)^2}
 \end{aligned}$$

### 3. TKE Budget in the ABL

$$\begin{aligned}
 \frac{\overline{\partial u_i'^2}}{\partial t} + \overline{U}_j \frac{\partial \overline{u_i'^2}}{\partial x_j} &= + 2 \delta_{i3} \frac{\overline{g(u_i' \theta_v')}}{\overline{\theta_v}} - 2 \overline{u_i' u_j'} \frac{\partial \overline{U}_i}{\partial x_j} - \frac{\partial (\overline{u_j' u_i'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{u_i' p'})}{\partial x_i} - 2\varepsilon \\
 \frac{\overline{\partial u'^2}}{\partial t} + \overline{U}_j \frac{\partial \overline{u'^2}}{\partial x_j} &= - 2 \overline{u' u_j'} \frac{\partial \overline{U}}{\partial x_j} - \frac{\partial (\overline{u_j' u'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{u' p'})}{\partial x} + \frac{2 \overline{p'} \partial u'}{\overline{\rho} \partial x} - 2\nu \left( \frac{\partial u'}{\partial x_j} \right)^2 \\
 \frac{\overline{\partial v'^2}}{\partial t} + \overline{U}_j \frac{\partial \overline{v'^2}}{\partial x_j} &= - 2 \overline{v' u_j'} \frac{\partial \overline{V}}{\partial x_j} - \frac{\partial (\overline{u_j' v'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{v' p'})}{\partial y} + \frac{2 \overline{p'} \partial v'}{\overline{\rho} \partial y} - 2\nu \left( \frac{\partial v'}{\partial x_j} \right)^2 \\
 \frac{\overline{\partial w'^2}}{\partial t} + \overline{U}_j \frac{\partial \overline{w'^2}}{\partial x_j} &= \frac{2 \overline{g(w' \theta_v')}}{\overline{\theta_v}} - 2 \overline{w' u_j'} \frac{\partial \overline{W}}{\partial x_j} - \frac{\partial (\overline{u_j' w'^2})}{\partial x_j} - \frac{2}{\overline{\rho}} \frac{\partial (\overline{w' p'})}{\partial z} + \frac{2 \overline{p'} \partial w'}{\overline{\rho} \partial z} - 2\nu \left( \frac{\partial w'}{\partial x_j} \right)^2
 \end{aligned}$$

# 4. Surface Layer Similarity Theory

**What is the Surface Layer??**

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- **Horizontal pressure gradient forces are weak, generally**

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- **Therefore, the divergences of turbulent momentum and heat fluxes must be negligibly small OR the fluxes must be constant**

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- Still one is sufficiently away from the surface so that divergences of viscous momentum flux and diffusion heat flux are negligible
- Horizontal pressure gradient forces are weak, generally
- Therefore, the divergences of turbulent momentum and heat fluxes must be negligibly small OR the fluxes must be constant
- **Surface Layer is the lowest few tens to hundreds of meter of the ABL where the turbulent momentum and heat fluxes are constant**

## 4. Surface Layer Similarity Theory

**Surface Layer closely corresponds to the Overlap Layer in Laboratory Turbulent Boundary Layers where the turbulent shear stress OR momentum flux is constant with respect to  $z$**

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**Surface Layer**

$\phi_M$  is dimensionless wind shear



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Surface Layer

$\phi_M$  is dimensionless wind shear

$$\frac{\kappa z}{U_*} \frac{\partial U}{\partial z} = \phi_M = f(\zeta)$$

**Proposal by Monin and Obukhov**

$f(\zeta = 0) = 1$  recovers the overlap layer scaling

## 4. Surface Layer Similarity Theory

### Dimensionless gradients in the Surface Layer

$$\phi_M = \frac{k z}{u_*} \frac{\partial \bar{U}}{\partial z}$$

$$\phi_H = \frac{k z}{\theta_*^{SL}} \frac{\partial \bar{\theta}}{\partial z}$$

$$\phi_E = \frac{k z}{q_*^{SL}} \frac{\partial \bar{q}}{\partial z}$$

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### Different Classes of Similarity Theories

- **Monin-Obukhov (Surface Layer) Similarity**
- **Mixed Layer Similarity**
- **Local Similarity**
- **Free Convection Similarity**
- **Rossby-Number Similarity**

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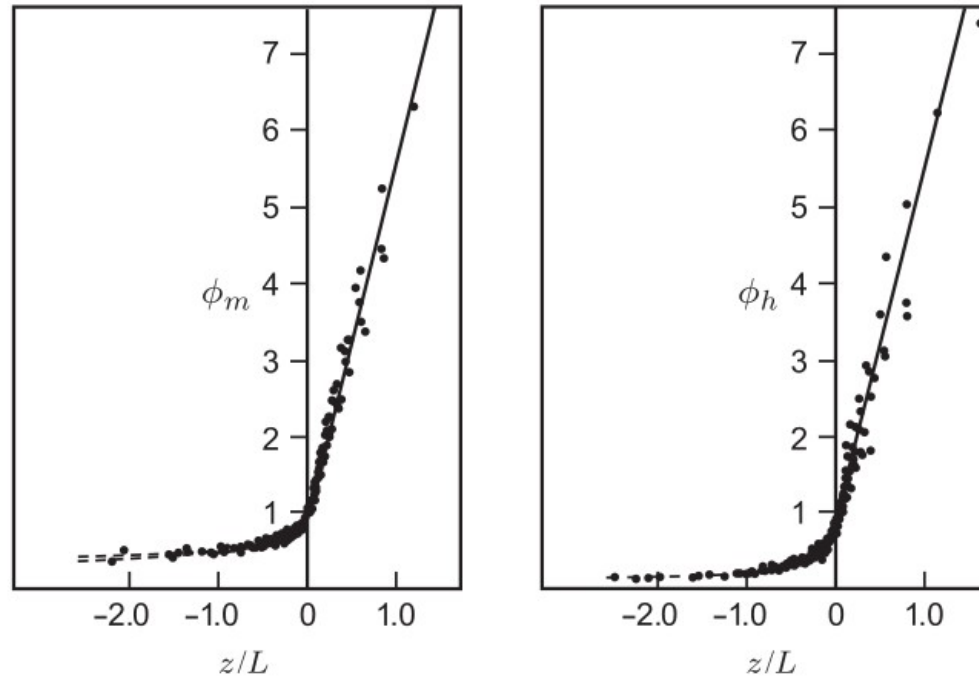
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### For Surface Layer Similarity

$\phi_M, \phi_H, \phi_E$  universal functions of  $\zeta$

## 4. Surface Layer Similarity Theory



**“Scaling” of  
Surface Layer data  
over a variety of  
stability conditions  
(Wyngaard)**

Figure 10.3 The M-O functions for mean wind shear (left) and mean potential temperature gradient (right), Eq. (10.12), from the 1968 Kansas experiment. From Businger *et al.* (1971).

## 4. Surface Layer Similarity Theory

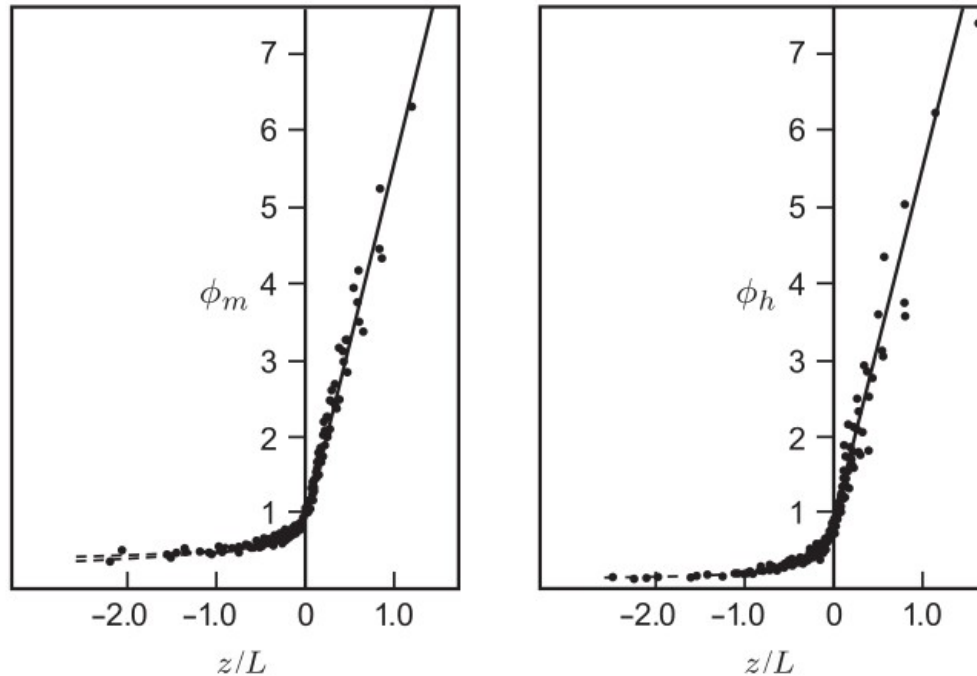


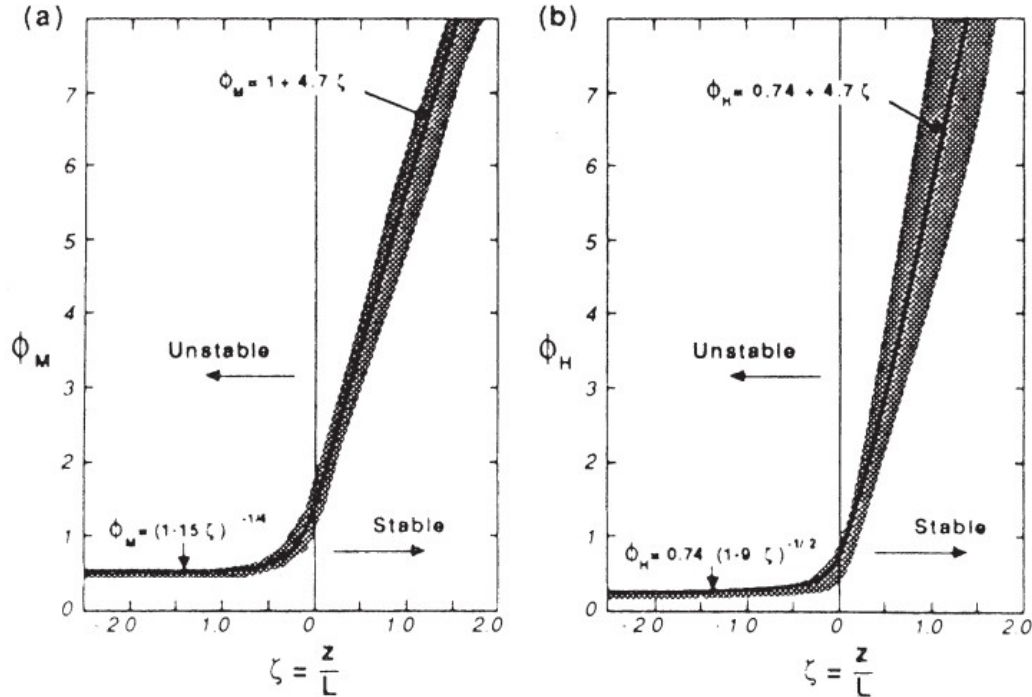
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**“Scaling” of  
Surface Layer data  
over a variety of  
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(Wyngaard)**

**“Curve Fit” equations  
for different portions of  
these universal curves  
are the Surface Layer  
Parameterizations**

**(Stull, pg. 355+)**

# 4. Surface Layer Similarity Theory



**Fig. 9.9** (a) Range of dimensionless wind shear observations in the surface layer, plotted with interpolation formulas. (b) Range of dimensionless temperature gradient observations in the surface layer, plotted with interpolation formulas. After Businger, et al. (1971).

$$\begin{aligned}
 \phi_M &= 1 + \left( \frac{4.7 z}{L} \right) && \text{for } \frac{z}{L} > 0 \text{ (stable)} \\
 \phi_M &= 1 && \text{for } \frac{z}{L} = 0 \text{ (neutral)} \\
 \phi_M &= \left[ 1 - \left( \frac{15z}{L} \right) \right]^{-1/4} && \text{for } \frac{z}{L} < 0 \text{ (unstable)} \\
 \\ 
 \phi_H &= \frac{K_m}{K_H} + \frac{4.7 z}{L} && \text{for } \frac{z}{L} > 0 \text{ (stable)} \\
 \phi_H &= \frac{K_m}{K_H} && \text{for } \frac{z}{L} = 0 \text{ (neutral)} \\
 \phi_H &= \frac{K_m}{K_H} \left[ 1 - \frac{9z}{L} \right]^{-1/4} && \text{for } \frac{z}{L} < 0 \text{ (unstable)}
 \end{aligned}$$

## 5. Prandtl's concept of a mixing length

$$\tau_{viscous} = \nu \frac{\partial U}{\partial z}$$



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$$\tau_{viscous} = \nu \frac{\partial U}{\partial z}$$

$$K_m \propto U_s L_s$$

$$\tau_{turbulent} = -\overline{u'w'} = K_m \frac{\partial U}{\partial z}$$

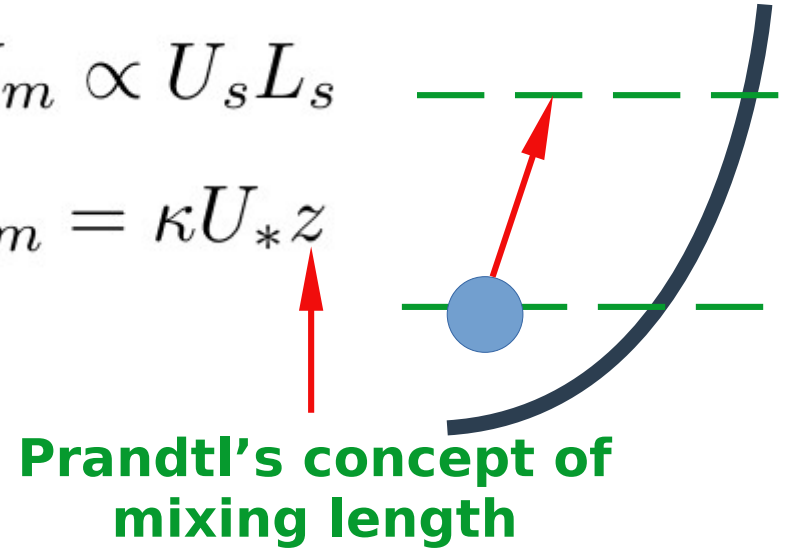
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$$K_m = \kappa U_* z$$



$\nu$  is property of the “fluid” and  $K_m$  is property of the “flow”

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Prandtl's concept of mixing length



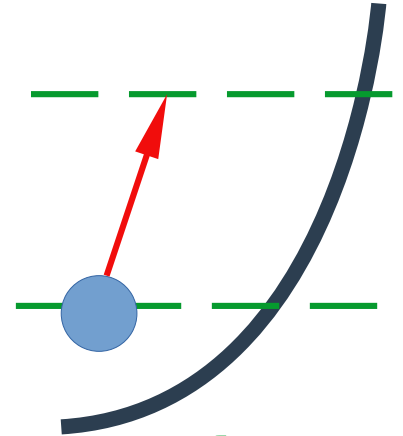
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Prandtl's concept of mixing length

$$K_m = \kappa^2 z^2 \frac{\partial U}{\partial z}$$

$$\tau_{turbulent} = -\overline{u'w'} = K_m \frac{\partial U}{\partial z}$$

$$-\overline{u'w'} = U_*^2$$

$$\frac{\partial U}{\partial z} = \frac{U_*}{\kappa z}$$

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## 6. Turbulence Closures or Parameterizations

**Page 197, Chapter  
6 from Stull**